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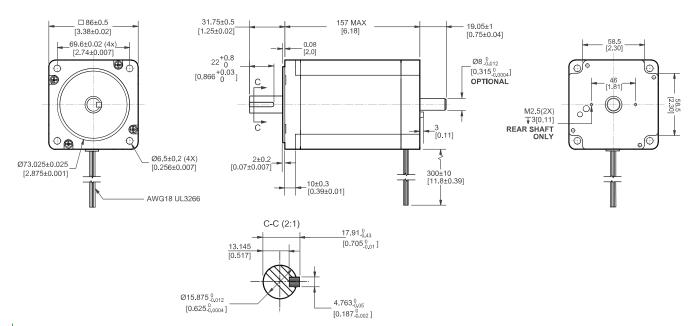
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Part Number	X8718-157-35
Step Angle	1.8°
Frame Size (mm/in)	86.00/3.390
"A" Body Length (mm/in)	157.00/6.180
Current (Amps/Phase)	3.5
Holding Torque (oz-in/Nm)	2124.18/15
Resistance (Ohms/Phase)	1.81
Rotor Inertia (g-cm²/ oz-in²)	2200/20.45
Number of Leads	4
Connection	Bipolar
Weight (lbs/kg)	11.31/5.13

# **DIMENSIONS**



## **PERFORMANCE CURVE**

#### **X8718-157-35** 48 VDC, 3.5 AMP, 1/2 stepping

12 10 8 8 4 2 0 0 200 400 600 800 1000 1200 1400 1600 1800

Speed (RPM)

#### **OPERATING SPECIFICATIONS**

Radial Play	0.03 mm @ 0.45 kg (0.001 in @ 1.00 lbs)
End Play	0.08 mm @ 1.36 kg (0.003 in @ 3.00 lbs)
Shaft Run Out	0.05 TIR (0.002 TIR)
Concentricity of Mounting Pilot to Shaft	0.08 TIR (0.003 TIR)
Perpendicularity of Mounting Pilot to Face	0.08 TIR (0.003 TIR)
Max Radial Load at Dimension "K" from mounting face	17.69 kg (39.00 lbs)
Dimension"K"	15.75 mm (0.62 in)
Max Axial Load	6.80 kg (15.00 lbs)
Maximum Case Temperature	80°C (176°F) Maximum
Ambient Temperature	-20°C to 50°C (-4 to 122°F)
Storage Temperature	-20°C to 100°C (-4 to 212°F)
Humidity Range (%)	85% or less, non-condensing
Magnet Wire Insulation	Class B 130 ° C
Insulation Resistance	100M Ohm at 500 VCD
Dielectric Strength	500 VCD for 1 min.

## **OPERATION & USAGE TIPS**



Do not disassemble motors; a significant reduction in motor performance will occur.



Do not machine shafts; this will have a negative effect on shaft run out and perpendicularity.



Do not disconnect motor from drive while in operation.



Do not use holding torque/detent torque of motor as a fail safe



Do not hold motor by lead wires.



Do not exceed the rated current; this wil burn the motor.

FAILURE TO COMPLY WITH THESE RECOMMENDATIONS WILL VOID ALL WARRANTY TERMS

### **RECOMMENDED**



Power Supply PW-150-24



Stepper Driver+Controller **R356** 



Stepper Driver **R710** 

# Motion Control, Solved.

**MOTOR ENGINEERING & MANUFACTURING** 





Quick Prototype Turnaround



